

A structure of the set of differential games solutions

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*13-th International Symposium on
Dynamical Games and Application
Wroclaw, Poland, June 30 – July 3, 2008*

Purpose and Problem

Purpose:

Determine the set of values of differential games.

Problem:

Let the function $\varphi(\cdot, \cdot) : [t_0, \vartheta_0] \times \mathbb{R}^n \rightarrow \mathbb{R}$ be given. Design finitely dimensional compacts P and Q , dynamic function $f : [t_0, \vartheta_0] \times \mathbb{R}^n \times P \times Q \rightarrow \mathbb{R}$ and payoff function $\sigma(\cdot) : \mathbb{R} \rightarrow \mathbb{R}$ such that function $\varphi(\cdot, \cdot)$ is a value of differential game

$$\dot{x} = f(t, x, u, v), \quad t \in [t_0, \vartheta_0], \quad x \in \mathbb{R}, \quad u \in P, \quad v \in Q$$

with payoff functional $\sigma(x(\vartheta_0))$.

Conditions on sets

P and Q are compacts in finitely dimensional space.

Conditions on f

F1. f is continuous;

F2. f is locally lipschitzian with respect to x ;

F3. for all $t \in [t_0, \vartheta_0]$, $x \in \mathbb{R}^n$, $u \in P$, $v \in Q$

$$\|f(t, x, u, v)\| \leq \Lambda_f(1 + \|x\|)$$

Conditions on σ

S1. σ is continuous;

S2. for all $x \in \mathbb{R}^n$

$$|\sigma(x)| \leq \Lambda_\sigma(1 + \|x\|).$$

Hamiltonian of Differential Game

We consider differential games in the class of *quasi-strategies of the first player* (advantage of the first player).

$$H(t, x, s) \triangleq \max_{v \in Q} \min_{u \in P} \langle s, f(t, x, u, v) \rangle.$$

Properties of Hamiltonian

H1. (sublinear growth condition) for all $(t, x, s) \in [t_0, \vartheta_0] \times \mathbb{R}^n \times \mathbb{R}^n$

$$|H(t, x, s)| \leq \Lambda_f \|s\| (1 + \|x\|);$$

H2. for every bounded region $A \subset \mathbb{R}^n$ there exist function $\omega_A \in \Omega$ and constant L_A such that for all $(t', x', s'), (t'', x'', s'') \in [t_0, \vartheta_0] \times A \times \mathbb{R}^n$ the following inequality holds:

$$\begin{aligned} \|H(t', x', s') - H(t'', x'', s'')\| &\leq \\ &\leq \omega(t' - t'') + L_A \|x' - x''\| + \\ &\quad + \Lambda_f (1 + \inf\{\|x'\|, \|x''\|\}) \|s_1 - s_2\|; \end{aligned}$$

H3. H is positively homogeneous with respect to the third variable: if $\alpha \geq 0$ then

$$H(t, x, \alpha s) = \alpha H(t, x, s).$$

Equation:

$$\frac{\partial \varphi(t, x)}{\partial t} + H\left(t, x, \frac{\partial \varphi(t, x)}{\partial x}\right) = 0;$$

Boundary condition:

$$\varphi(\vartheta_0, x) = \sigma(x).$$

Minimax Solution [A.I. Subbotin]

Function φ is a *minimax solution* if for all $(t, x) \in (t_0, \vartheta_0) \times \mathbb{R}^n$ the following inequalities hold:

$$a + H(t, x, s) \leq 0 \quad \forall (a, s) \in D_D^- \varphi(t, x);$$

$$a + H(t, x, s) \geq 0 \quad \forall (a, s) \in D_D^+ \varphi(t, x);$$

Lower Dini Derivative

Let $\tau \in \mathbb{R}$, $g \in \mathbb{R}^n$.

$$d_{\mathbb{D}}^{-}\varphi(t, x; \tau, g) \triangleq \liminf_{\delta \rightarrow 0} \frac{\varphi(t + \delta\tau, x + \delta g) - \varphi(t, x)}{\delta}$$

Dini Subdifferential

$$D_{\mathbb{D}}^{-}\varphi(t, x) \triangleq \{(a, s) \in \mathbb{R} \times \mathbb{R}^n : \forall (\tau, g) \in \mathbb{R} \times \mathbb{R}^n \\ a\tau + \langle s, g \rangle \leq d_{\mathbb{D}}^{-}\varphi(t, x; \tau, g)\}.$$

Upper Dini Derivative

Let $\tau \in \mathbb{R}$, $g \in \mathbb{R}^n$.

$$d_{\text{D}}^+ \varphi(t, x; \tau, g) \triangleq \limsup_{\delta \rightarrow 0} \frac{\varphi(t + \delta\tau, x + \delta g) - \varphi(t, x)}{\delta}$$

Dini Superdifferential

$$D_{\text{D}}^+ \varphi(t, x) \triangleq \{(a, s) \in \mathbb{R} \times \mathbb{R}^n : \forall (\tau, g) \in \mathbb{R} \times \mathbb{R}^n \\ a\tau + \langle s, g \rangle \geq d_{\text{D}}^+ \varphi(t, x; \tau, g)\}.$$

If $D_D^- \varphi(t, x) \neq \emptyset$ and $D_D^+ \varphi(t, x) \neq \emptyset$ simultaneously, then $(t, x) \in J$ and

$$D_D^- \varphi(t, x) = D_D^+ \varphi(t, x) = \{(\partial \varphi(t, x) / \partial t, \nabla \varphi(t, x))\}.$$

Here

- $(\partial \varphi(t, x) / \partial t, \nabla \varphi(t, x))$ is total derivative;
- J denotes the set of points x at which function φ is differentiable. By the Rademacher's theorem measure $[t_0, \vartheta_0] \times \mathbb{R}^n \setminus J$ is 0.

Lower Clarke derivative

$$d_{\text{Cl}}^- \varphi(t, x; \tau, g) \triangleq \liminf_{x' \rightarrow x, t' \rightarrow t, \alpha \rightarrow 0} \frac{1}{\alpha} (\varphi(t' + \alpha\tau, x' + \alpha g) - \varphi(t', x')).$$

Upper Clarke derivative

$$d_{\text{Cl}}^+ \varphi(t, x; \tau, g) \triangleq \limsup_{x' \rightarrow x, t' \rightarrow t, \alpha \rightarrow 0} \frac{1}{\alpha} (\varphi(t' + \alpha\tau, x' + \alpha g) - \varphi(t', x')).$$

Clarke subdifferential

There exists convex compact $\partial_{\text{Cl}} \varphi(t, x) \subset \mathbb{R} \times \mathbb{R}^n$ such that

$$d_{\text{Cl}}^- \varphi(t, x; \tau, g) = \min_{(a,s) \in \partial_{\text{Cl}} \varphi(t,x)} [a\tau + \langle s, g \rangle],$$

$$d_{\text{Cl}}^+ \varphi(t, x; \tau, g) = \max_{(a,s) \in \partial_{\text{Cl}} \varphi(t,x)} [a\tau + \langle s, g \rangle].$$

Inclusions

$$D_D^- \varphi(t, x) \subset \partial_{C1} \varphi(t, x), \quad D_D^+ \varphi(t, x) \subset \partial_{C1} \varphi(t, x).$$

Representation

$$\partial_{C1} \varphi(t, x) = \text{co}\{(a, s) : \exists \{t_i, x_i\}_{i=1}^{\infty} \subset J : \\ a = \lim_{i \rightarrow \infty} \partial \varphi(t_i, x_i) / \partial t, \quad s = \lim_{i \rightarrow \infty} \nabla \varphi(t_i, x_i)\}.$$

Let $\varphi : [t_0, \vartheta_0] \times \mathbb{R}^n \rightarrow \mathbb{R}$ be local lipschitzian function such that $\varphi(\vartheta_0, \cdot)$ satisfies sublinear growth condition.

Procedure

- 1 Design a set $\mathbb{E} \subset [t_0, \vartheta_0] \times \mathbb{R}^n \times \mathbb{R}^n$ and function $h : \mathbb{E} \rightarrow \mathbb{R}^n$ in accordance with the function φ .
- 2 If the set \mathbb{E} and functions h and φ satisfy some conditions, function φ is a value of some differential game.
- 3 Extend h to the whole space $[t_0, \vartheta_0] \times \mathbb{R}^n \times \mathbb{R}^n$.
- 4 Design control spaces P, Q and a dynamical function f in accordance with the extension of h .

$$\mathbb{E} = \mathbb{E}_1 \cup \mathbb{E}_2;$$

$$\mathbb{E}_i = \{(t, x, s) : (t, x) \in [t_0, \vartheta_0] \times \mathbb{R}^n, s \in E_i(t, x)\} \quad i = 1, 2.$$

Set-valued maps $E_1(t, x)$ and $E_2(t, x)$ are defined below.

Let $(t, x) \in J$. Put

$$E_1(t, x) \triangleq \{\nabla\varphi(t, x)\};$$

$$h(t, x, \nabla\varphi(t, x)) \triangleq -\frac{\partial\varphi(t, x)}{\partial t}.$$

Condition (E1)

For any position $(t_*, x_*) \notin J$ and any sequences $\{(t'_i, x'_i)\}_{i=1}^\infty, \{(t''_i, x''_i)\}_{i=1}^\infty \subset J$ such that $(t'_i, x'_i) \rightarrow (t_*, x_*)$, $i \rightarrow \infty$, $(t''_i, x''_i) \rightarrow (t_*, x_*)$, $i \rightarrow \infty$, the following implication holds:

$$\begin{aligned} \left(\lim_{i \rightarrow \infty} \nabla\varphi(t'_i, x'_i) = \lim_{i \rightarrow \infty} \nabla\varphi(t''_i, x''_i)\right) \Rightarrow \\ \left(\lim_{i \rightarrow \infty} h(t'_i, x'_i, \nabla\varphi(t'_i, x'_i)) = \lim_{i \rightarrow \infty} h(t''_i, x''_i, \nabla\varphi(t''_i, x''_i))\right). \end{aligned}$$

Points of nondifferentiability

Limit Directions

Let $(t, x) \notin J$. Put

$$E_1(t, x) \triangleq \{s \in \mathbb{R}^n : \exists \{(t_i, x_i)\} \subset J : \\ \lim_{i \rightarrow \infty} (t_i, x_i) = (t, x) \ \& \ \lim_{i \rightarrow \infty} \nabla \varphi(t_i, x_i) = s\}.$$

$E_1(t, x)$ is nonempty and bounded.

Hamiltonian in limit directions

$$h(t, x, s) \triangleq \lim_{i \rightarrow \infty} h(t_i, x_i, \nabla \varphi(t_i, x_i)) \\ \forall \{(t_i, x_i)\} \subset J : \lim_{i \rightarrow \infty} (t_i, x_i) = (t, x) \ \& \ s = \lim_{i \rightarrow \infty} \nabla \varphi(t_i, x_i).$$

Property

$$\partial_{\text{Cl}} \varphi(t, x) = \text{co}\{(-h(t, x, s), s) : s \in E_1(t, x)\}.$$

$$CJ^- \triangleq \{(t, x) \in (t_0, \vartheta_0) \times \mathbb{R}^n \setminus J : D_D^- \varphi((t, x)) \neq \emptyset\};$$

$$CJ^+ \triangleq \{(t, x) \in (t_0, \vartheta_0) \times \mathbb{R}^n \setminus J : D_D^+ \varphi((t, x)) \neq \emptyset\}.$$

Property: $CJ^- \cap CJ^+ = \emptyset$.

If $(t, x) \in CJ^-$,

$$E_2(t, x) \triangleq \{s \in \mathbb{R}^n : \exists a \in \mathbb{R} : (a, s) \in D_D^- \varphi((t, x))\} \setminus E_1(t, x);$$

if $(t, x) \in CJ^+$,

$$E_2(t, x) \triangleq \{s \in \mathbb{R}^n : \exists a \in \mathbb{R} : (a, s) \in D_D^+ \varphi((t, x))\} \setminus E_1(t, x);$$

if $(t, x) \in ([t_0, \vartheta_0] \times \mathbb{R}^n) \setminus (CJ^- \cup CJ^+)$

$$E_2(t, x) \triangleq \emptyset.$$

$$E(t, x) \triangleq E_1(t, x) \cup E_2(t, x).$$

$$E^\natural(t, x) \triangleq \{\|s\|^{-1}s : s \in E(t, x) \setminus \{0\}\}.$$

Subsets of $[t_0, \vartheta_0] \times \mathbb{R}^n \times \mathbb{R}^n$

$$\mathbb{E}_1 \triangleq \{(t, x, s) : (t, x) \in [t_0, \vartheta_0] \times \mathbb{R}^n, s \in E_1(t, x)\},$$

$$\mathbb{E}_2 \triangleq \{(t, x, s) : (t, x) \in [t_0, \vartheta_0] \times \mathbb{R}^n, s \in E_2(t, x)\},$$

$$\mathbb{E} \triangleq \mathbb{E}_1 \cup \mathbb{E}_2 = \{(t, x, s) : (t, x) \in [t_0, \vartheta_0] \times \mathbb{R}^n, s \in E(t, x)\}.$$

$$\mathbb{E}^\natural \triangleq \{(t, x, s) : (t, x) \in [t_0, \vartheta_0] \times \mathbb{R}^n, s \in E^\natural(t, x)\}.$$

Let $\varphi : [t_0, \vartheta_0] \times \mathbb{R}^n \rightarrow \mathbb{R}$ be local lipschitzian function such that $\varphi(\vartheta_0, \cdot)$ satisfies sublinear growth condition.

Theorem

Function φ is a value of some differential game with terminal payoff functional if and only if the function h defined on \mathbb{E}_1 is extendable on the set \mathbb{E}_2 such that conditions (E1)–(E4) hold. (Conditions (E2)–(E4) are defined below.)

Condition (E2)

If $(t, x) \in CJ^-$ then for any $s_1, \dots, s_{n+2} \in E_1(t, s)$
 $\lambda_1, \dots, \lambda_{n+2} \in [0, 1]$ such that

$$\sum \lambda_k = 1, \quad \left(-\sum \lambda_k h(t, x, s_k), \sum \lambda_k s_k\right) \in D^- \varphi(t, x)$$

the following inequality holds:

$$h\left(t, x, \sum_{k=1}^{n+2} \lambda_k s_k\right) \leq \sum_{k=1}^{n+2} \lambda_k h(t, x, s_k);$$

If $(t, x) \in CJ^+$ then for any $s_1, \dots, s_{n+2} \in E_1(t, s)$
 $\lambda_1, \dots, \lambda_{n+2} \in [0, 1]$ such that

$$\sum \lambda_k = 1, \quad \left(-\sum \lambda_k h(t, x, s_k), \sum \lambda_k s_k\right) \in D^+ \varphi(t, x)$$

the following inequality holds:

$$h\left(t, x, \sum_{k=1}^{n+2} \lambda_k s_k\right) \geq \sum_{k=1}^{n+2} \lambda_k h(t, x, s_k);$$

Condition (E3)

Condition (E3)

- if $0 \in E(t, x)$, then $h(t, x, 0) = 0$;
- if $s_1 \in E(t, x)$ and $s_2 \in E(t, x)$ are codirectional (i.e. $\langle s_1, s_2 \rangle = \|s_1\| \cdot \|s_2\|$), then

$$\|s_2\|h(t, x, s_1) = \|s_1\|h(t, x, s_2).$$

Function $h^\natural : \mathbb{E}^\natural \rightarrow \mathbb{R}$

$\forall (t, x) \in [t_0, \vartheta_0] \times \mathbb{R}^n \quad \forall s \in E(t, x) \setminus \{0\}$

$$h^\natural(t, x, \|s\|^{-1}s) \triangleq \|s\|^{-1}h(t, x, s).$$

Sublinear growth condition

there exists $\Gamma > 0$ such that for any $(t, x, s) \in \mathbb{E}^{\natural}$ the following inequality is fulfilled

$$h^{\natural}(t, x, s) \leq \Gamma(1 + \|x\|).$$

Difference estimate

For every bounded region $A \subset \mathbb{R}^n$ there exist $L_A > 0$ and modulus of continuity ω_A such that for any $(t', x', s'), (t'', x'', s'') \in \mathbb{E}^{\natural} \cap [t_0, \vartheta_0] \times A \times \mathbb{R}^n$ the following inequality is fulfilled

$$\begin{aligned} \|h^{\natural}(t', x', s') - h^{\natural}(t'', x'', s'')\| &\leq \omega_A(t' - t'') + \\ &+ L_A \|x' - x''\| + \Gamma(1 + \inf\{\|x'\|, \|x''\|\}) \|s' - s''\|. \end{aligned}$$

A method of extension

Let $\varphi : [t_0, \vartheta_0] \times \mathbb{R}^n \rightarrow \mathbb{R}$ be local lipschitzian function such that $\varphi(\vartheta_0, \cdot)$ satisfies sublinear growth condition.

Corollary

Suppose that h as function defined on \mathbb{E}_1 satisfies the condition (E1). Suppose also that the extension of h on \mathbb{E}_2 given by the following rule is well defined: for all $(t, x) \in CJ^- \cup CJ^+$, $s \in E_2(t, x)$, $s_1, \dots, s_{n+2} \in E_1(t, x)$, $\lambda_1, \dots, \lambda_{n+2} \in [0, 1]$ such that $\sum \lambda_i = 1$ $\sum \lambda_i s_i = s$

$$h(t, x, s) \triangleq \sum_{i=1}^{n+2} \lambda_i h(t, x, s_i).$$

If function $h : \mathbb{E} \rightarrow \mathbb{R}$ satisfies the conditions (E3) and (E4), then φ is a value of some differential game with terminal payoff functional.

Positive Example

Let $n = 2$, $t_0 = 0$, $\vartheta_0 = 1$.

$$\varphi_1(t, x_1, x_2) = t + |x_1| - |x_2|.$$

For $x_1, x_2 \neq 0$ $h(t, x_1, x_2; \operatorname{sgn}x_1, \operatorname{sgn}x_2) = -1.$

For $x_1 = 0, x_2 \neq 0$ $h(t, 0, x_2; \pm 1, \operatorname{sgn}x_2) = -1.$

For $x_1 \neq 0, x_2 = 0$ $h(t, x_1, 0; \operatorname{sgn}x_1, \pm 1) = -1.$

For $x_1 = x_2 = 0$ $h(t, 0, 0; \pm 1, \pm 1) = -1.$

$$J = \{(t, x_1, x_2) : x_1 x_2 \neq 0\}.$$

$$CJ^- = \{(t, 0, x_2) : x_2 \neq 0\},$$

$$CJ^+ = \{(t, x_1, 0) : x_1 \neq 0\}.$$

The extension is designed with the help of Corollary.

Negative Example

Let $n = 2$, $t_0 = 0$, $\vartheta_0 = 1$.

$$\varphi_2(t, x_1, x_2) = t(|x_1| - |x_2|).$$

$$J = \{(t, x_1, x_2) : t \in (0, 1), x_1 x_2 \neq 0\}.$$

For $(t, x) \in J$ $E(t, x) = \{(t \cdot \operatorname{sgn} x_1, t \cdot \operatorname{sgn} x_2)\}$.

$$h(t, x_1, x_2; t \cdot \operatorname{sgn} x_1, t \cdot \operatorname{sgn} x_2) = |x_1| - |x_2|.$$

Sets

$$\mathbb{E}_0 \triangleq \{(t, x_1, x_2; t \operatorname{sgn} x_1, t \operatorname{sgn} x_2) : (t, x_1, x_2) \in J\}.$$

$$\mathbb{E}_0^{\natural} \triangleq \{(t, x_1, x_2; \operatorname{sgn} x_1 / \sqrt{2}, \operatorname{sgn} x_2 / \sqrt{2}) : (t, x_1, x_2) \in J\}.$$

Restriction of h^{\natural} on \mathbb{E}_0^{\natural} . Let $(t, x_1, x_2) \in J$

$$h^{\natural}(t, x_1, x_2; \operatorname{sgn} x_1 / \sqrt{2}, \operatorname{sgn} x_2 / \sqrt{2}) = \frac{|x_1| - |x_2|}{\sqrt{2}t}.$$

Step 0

Define payoff functional by formula $\sigma(\cdot) \triangleq \varphi(\vartheta_0, \cdot)$

Step 1

- Extend function h^{\natural} defined on \mathbb{E}^{\natural} to the set $[t_0, \vartheta_0] \times \mathbb{R}^n \times S^{(n-1)}$. ($S^{(k)}$ is k -dimensional sphere). Denote this extension by h^* .
- Design the positively homogeneous function $H : [t_0, \vartheta_0] \times \mathbb{R}^n \times \mathbb{R}^n \rightarrow \mathbb{R}$ which is an extension of h^* .

Step 2







Design finitely dimensional compacts P, Q and function f in accordance with H .

Corollary

If $\varphi(\cdot, \cdot)$ is a value of differential game with advantage of the *first player*, then $\varphi(\cdot, \cdot)$ is a value of some differential game with advantage of the *second player*. The converse is also true.

Case $n = 1$

The set of values of all-possible differential games coincides with the set of values of differential game which satisfies Isaacs condition.

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